CHEAT SHEET STAT111

Statistical Methods - Tommy Odland - Last edit: June 13, 2018

\triangleright Basics

• The conditional distribution of Y given X is

$$f_{Y|X}(y|x) = \frac{f(x,y)}{f_X(x)}$$

- It can be shown that $\mathbf{E}[Y] = \mathop{\mathbf{E}}_{x} \left[\mathop{\mathbf{E}}_{y}[Y|X] \right].$
- The marginal distribution is $f_X(x) = \int f(x, y) \, dy$.
- The **variance** of a sum is given by

$$\mathbf{V}\left[\sum_{i} a_{i} X_{i}\right] = \sum_{i} \sum_{j} a_{i} a_{j} \operatorname{Cov}[X_{i}, X_{j}].$$

– The correlation ρ_{XY} is a scaled covariance:

$$\rho_{XY} = \frac{\sigma_{XY}}{\sigma_X \sigma_Y}, \text{ where } \sigma_{XY} = \operatorname{Cov}[X_i, X_j].$$

- The expected value is $E[h(x)] = \int p(x)h(x) dx$.
- A useful shortcut is $V[X] = E[X^2] E[X]^2$.
- When the skew $E[(X \mu)^3]/\sigma^3$ is positive, the right tail is longer or fatter.

⊳Probability functions

- If a cont. mapping Y = g(X) is monotonic with inverse X = h(Y), then $f_Y(y) = f_X(x) |h'(y)|$.
 - The generalization uses the Jacobian $|\det \frac{\partial(\boldsymbol{x})}{\partial(\boldsymbol{y})}|$.
- The r'th order moment of X is $E[X^r]$.
- The moment generating function (MGF) of X is defined as $M_X(t) = \mathbb{E}\left[e^{tX}\right]$.
 - It uniquely defines f(x) if it's valid for a range including zero.
 - Defines the moments by $\partial_t^r M_X(t)|_{t=0} = \mathbb{E}[X^r].$
 - If $R_X(t) = \ln M_X(t)$, then $\mu = R'_X(0)$ and $\sigma = R''_X(0)$.
 - $-Y = \sum_{i} a_i X_i$, iff $M_Y(t) = \prod_i M_{X_i}(a_i t)$
- Discrete probability mass functions
 - $-\exp(\lambda) = \lambda e^{-\lambda x}, x \ge 0$
 - poisson $(\lambda) = \lambda^x e^{-\lambda} / x!$, $x \ge 0$
- Continuous probability density functions
 - The gamma function is $\Gamma(k) = \int_0^\infty x^{k-1} e^{-x} dx$.
 - $-\operatorname{norm}(\mu,\sigma) = \exp(-(x-\mu)^2/2\sigma^2)/\sqrt{2\pi}\sigma$
 - X is lognormally distributed if $\log(X) \sim \text{norm.}$
 - The Weibull distribution is defined for $x \ge 0$ as

$$f(x; \alpha, \beta) = \frac{\alpha}{\beta^{\alpha}} x^{\alpha - 1} \exp\left(-(x/\beta)^{\alpha}\right),$$

where α is a location parameter, β is a scale parameter and $f(x; \alpha, \beta)$ may be shifted too.

- The student-t distribution is the distribution of

$$T = \frac{Z}{\sqrt{X/\nu}} \cong \frac{X-\mu}{S/\sqrt{n}},$$

where $Z \sim \text{norm}$ and $X \sim \chi^2_{\nu}$.

- The Chi-squared distribution is the distribution of a sum of standard normals, i.e. $\chi^2_{\nu} = Z_1^2 + \cdots + Z_{\nu}^2$.
- The f-squared distribution is the distribution of

$$F = \frac{\chi_{\nu_1}^2 / \nu_1}{\chi_{\nu_2}^2 / \nu_2}.$$

- The standard beta distribution on [0, 1] is

$$f(x;\alpha,\beta) = \frac{\Gamma(\alpha+\beta)}{\Gamma(\alpha)\Gamma(\beta)} x^{\alpha-1} (1-x)^{\beta-1}$$

⊳Order statistics

- The order statistics of X_1, \ldots, X_n is obtained by sorting the random variables, yielding Y_1, \ldots, Y_n .
- The CDF of Y_1 (smallest value) is

$$P(Y_1 < y) = 1 - [1 - P(Y < y)]^n$$

• The CDF of Y_n (largest value) is

$$P(Y_n < y) = [P(Y \le y)]^n$$

• The joint pdf of Y_1, \ldots, Y_n is given by

 $g(y_1,\ldots,y_n) = n! f(y_1) \times \ldots \times f(y_n).$

⊳Point estimation and CIs

- A point estimate $\hat{\theta}$ is a sample based value for θ .
- Moment estimators equate theoretical moments $E[X^r] = \int f(x)x^r dx$ with sample moments $n^{-1} \sum_i X_i^r$ to estimate θ . Simple, often biased.
- Three criteria for choosing $\hat{\theta}$:
 - No bias, choose $E[\hat{\theta}] = \theta$.
 - If no bias, choose minimum variance $V[\hat{\theta}]$.
 - Trade-off between bias and variance: min MSE.
- The mean squared error of an estimator is $MSE[\hat{\theta}] = E[(\hat{\theta}-\theta)^2] = V[\hat{\theta}] + E[\hat{\theta}-\theta]^2 = var+bias^2$
- Confidence interval for μ when σ is known:

$$\mu_0 \pm z_{\alpha/2} \frac{\sigma}{\sqrt{n}}$$

• Confidence interval for μ when σ is unknown:

$$\mu_0 \pm t_{\alpha/2, n-1} \frac{s}{\sqrt{n}}$$

• Confidence interval for σ^2 :

$$\frac{(n-1)s^2}{\chi^2_{\alpha/2,n-1}} < \sigma^2 < \frac{(n-1)s^2}{\chi^2_{1-\alpha/2,n-1}}$$

• Two approaches to **bootstrap** CI for \bar{x} :

- Use
$$\bar{x} \pm z_{\alpha/2} s_{\rm b}$$
, where $s_{\rm b}^2 = \sum_i^n (\bar{x}_i^* - \bar{x}^*)^2 / (n-1)$

– Bootstrap, compute $n \bar{x}_i^*$'s, use percentiles.

\triangleright Tests

- In a z-test for differences, the hypothesis is that $\mu_1 - \mu_2 = \Delta_0$, and σ_1 and σ_2 are both known. Combine standard deviations and test with z-test. Either X and Y are normal, or CLT applies.
- In a *t*-test for differences, the hypothesis is that $\mu_1 \mu_2 = \Delta_0$, and $\sigma_{1,2}$ are both unknown. Combine s_1 and s_2 and use *t*-test. Degrees of freedom is found in an involved expression.
 - If $\sigma_1 = \sigma_2$, but both are unknown, pool them

$$S_p^2 = \frac{m-1}{m+n-2}s_1^2 + \frac{n-1}{m+n-2}s_2^2$$

and employ a *t*-test with m + n - 2 df.

- A **Type I** error is rejecting H_0 when H_0 is true. A **Type II** error is keeping H_0 when H_0 is false.
- The power function is $\beta(\mu) = P_{\mu}$ (rejecting H_0).

$\triangleright ANOVA$

• In one-way **ANOVA**, the hypotheses are

$$H_0: \quad \mu_1 = \mu_2 = \dots = \mu_I$$
$$H_0: \quad \text{at least } 1 \ \mu_i \neq \mu_j$$

Assumes normal distributions and same variance.

• The sum of squares are

$$SSTr = J \sum_{i} \left(\bar{Y}_{i.} - \bar{Y}_{..} \right)^2 \qquad (between-group)$$

$$SSE = \sum_{i} \sum_{j} \left(Y_{ij} - \bar{Y}_{i} \right)^{2} \qquad \text{(within-group)}$$

$$SST = SSTr + SSE$$
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 $MSTr = \frac{SSTr}{I-1} \quad MSE = \frac{SSE}{I(J-1)} \quad f = \frac{MSTr}{MSE}$

- The ratio is distributed as $f \sim F_{I-1,I(J-1)}$
- Under the null hypothesis, SSTr ~ χ^2_{I-1} , SSE ~ $\chi^2_{I(J-1)}$ and SST ~ χ^2_{IJ-1} .
- To test for differences, sort μ_i 's, form the interval

$$\bar{x}_{i\cdot} - \bar{x}_{j\cdot} \pm Q_{\alpha,I,I(J-1)} \sqrt{\mathrm{MSE}/J}$$

and extend lines to test for significant differences.

\triangleright Regression

• Assume $y_i = \beta_0 + \beta_1 x_i + \epsilon_i$, where ϵ_i are i.i.d. standard normals.

– Implies $E[\epsilon_i] = 0$, $V[\epsilon] = \sigma^2$ and independence.

- $S_{xx} = \sum_{i} (x_i \bar{x})^2 = \sum_{i} x_i^2 n^{-1} (\sum_{i} x_i)^2$ • In $y = \hat{\beta}_0 + \hat{\beta}_1 x$, we compute $\hat{\beta}_1$ and $\hat{\beta}_0$ as:
- If $y = \beta_0 + \beta_1 x$, we compute β_1 and β_0 as $-\hat{\beta}_1 = S_{xy}/S_{xx}$ and $\hat{\beta}_0 = \bar{y} - \bar{x}\beta_1$
- The coefficient of determination r^2 is given by

$$r^{2} = 1 - \frac{\text{SSE}}{\text{SST}} = 1 - \frac{\sum_{i} (y_{i} - \hat{y}_{i})^{2}}{\sum_{i} (y_{i} - \bar{y})^{2}} = 1 - \frac{\text{res. }\sigma^{2}}{\text{tot. }\sigma^{2}}$$

The empirical correlation is $\rho = \sqrt{r^2}$.

• Interference about $\hat{\beta}_1$, i.e. $\hat{\beta}_1 \pm t_{\alpha/2,n-2} s_{\hat{\beta}_1}$.

- V[
$$\hat{\beta}_1$$
] = $\sigma_{\hat{\beta}_1}^2 = \sigma^2 / S_{xx}$, where $\sigma^2 = \text{SSE}/(n-2)$.

- Sample correlation coefficient: $S_{xy}/(\sqrt{S_{xx}}\sqrt{S_{yy}})$.
- Confidence interval interference of $\mu_{Y|X}$, which is deterministic. Prediction interval interference of future Y values, which is stochastic.

⊳Goodness-of-fit tests

• Goodness-of-fit tests are based on

$$\chi^2 = \sum_{i}^{n} \frac{(\text{obs}_i - \text{expected}_i)^2}{\text{expected}_i} \quad (\text{valid if } np_i \ge 5)$$

which has $\sim \chi^2_{n-1-m}$ degrees of freedom (*m* is the number of estimated parameters used to compute p_i), or alternatively $\sim \chi^2_{(I-1)(J-1)}$ if it's a contingency table.

\triangleright Nonparametrics

- The Wilcoxon signed rank test has $H_0: \mu = \mu_0$. Subtract μ_0 , rank the data by absolute value, then re-assign the signs. If H_0 is true, the sum of the positive ranks S_+ should be relatively small. Assumes symmetric distribution.
- The Wilcoxon ranked sum test has $H_0: \mu_A = \mu_B$. Assume *m* data points from *A* and *n* from *B*. Concatenate data, rank it, and sum ranks *W* associated with data from *A*. If H_0 is true, *W* will be somewhere in the middle of

$$\frac{m(m+1)}{2} \le W \le \frac{n(n+2m+1)}{2}$$

Assumes identical distribution shapes.

⊳References

• Jay L. Devore. *Modern Mathematical Statistics with Applications.* 2nd ed. Springer Texts in Statistics. Dordrecht: Springer, 2011.